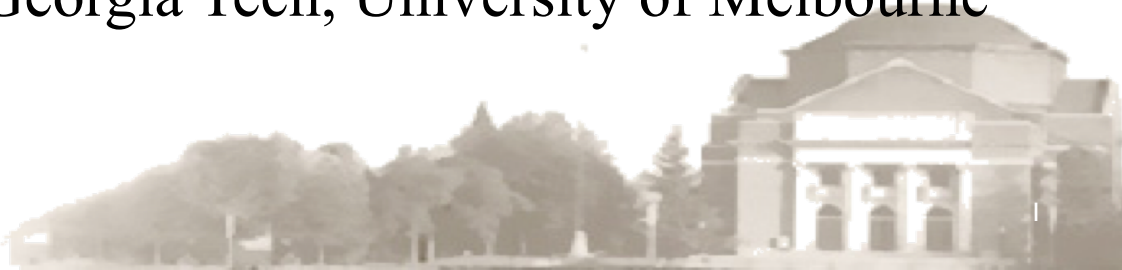


# Iterative Learning with Open-set Noisy Labels

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# Types of Noisy Labels

- **Closed-set noisy labels**
  - *A noisy sample possesses a true class that is **contained** within the set of known classes in the training data*
- **Open-set noisy labels:**
  - *A noisy sample possesses a true class that is **not contained** within the set of known classes in the training data*

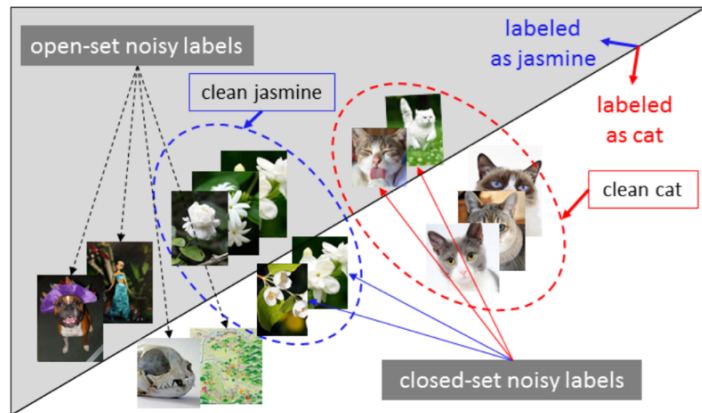


Figure 1. An illustration of closed-set vs open-set noisy labels.

Table 1. Types of labels for a “jasmine-cat” dataset.

	labeled as “jasmine”	labeled as “cat”
true “jasmine”	clean	closed-set
true “cat”	closed-set	clean
other class images	open-set	open-set



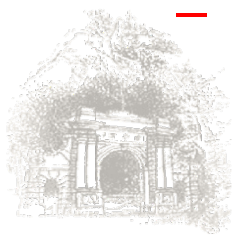
# Different methods to handle different noise

- Closed-set noisy labels

- *loss correction*
- *noise model based clean label inferring*

- Open-set noisy labels

- *loss or label correction may be inaccurate since the true class may not exist in the dataset*
- *Iterative learning framework to pull away noisy samples from clean samples in the deep representation space*



# Iterative learning framework

- Iterative noisy label detection:

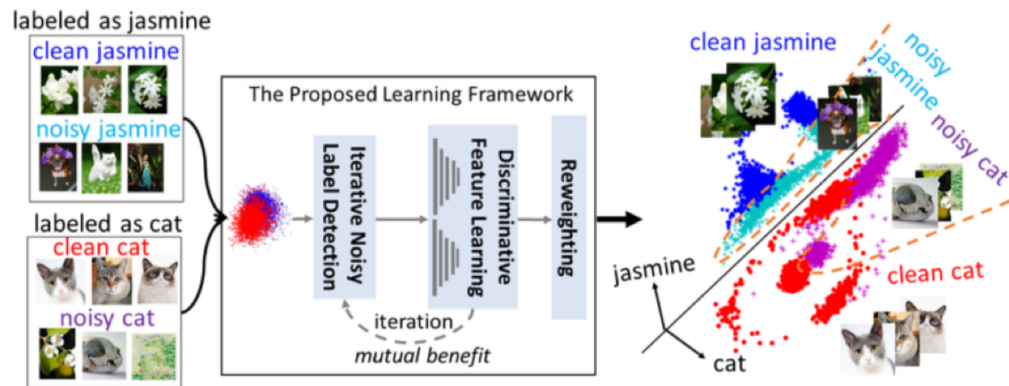
- *iteratively detect noisy labels based on the features of the network*

- Discriminative feature learning:

- *imposes a representation constraint via contrastive loss to pull away noisy samples from clean samples in the deep representation space*

- Reweighting:

- *express a relative confidence of clean and noisy labels on the representation learning*



# Experiments

- True noisy label rate:

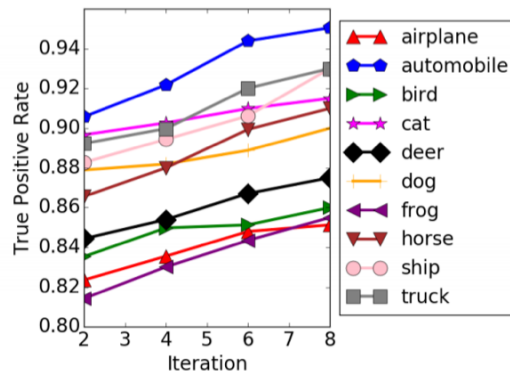


Figure 5. The true positive rate of the detected noisy labels over iteration on CIFAR-10+CIFAR-100 (40% open-set noise).

- Visualization of the learned features:

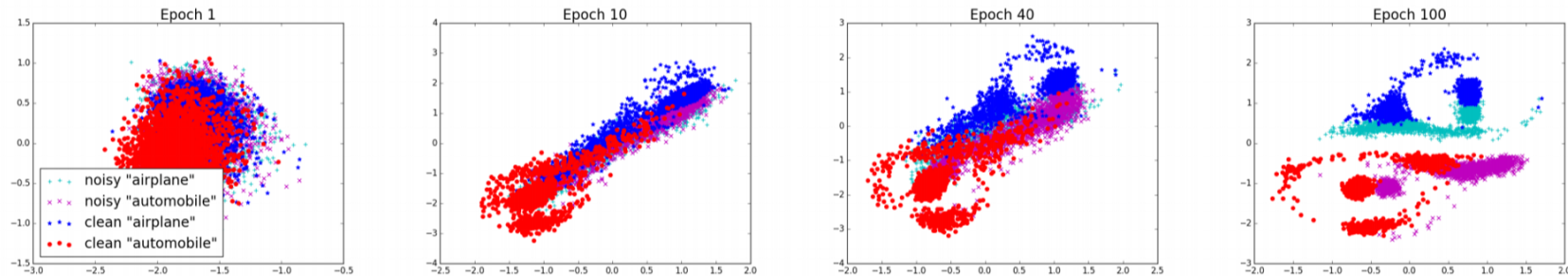


Figure 7. Visualization of the learned features. This visualization experiment uses a 2-class subset of CIFAR-10+CIFAR-100 (40% open-set noise) by setting the output feature dimension as 2.

# Experiments

## ● Ablation study:

Table 4. Accuracies (%) on CIFAR-10+CIFAR-100 (20% & 40% open-set noise) after removing (w/o) each module from our model.

Method	CIFAR-10+CIFAR-100	
	20% noise	40% noise
Our model	81.96	79.28
(a) w/o reweighting		
-- case $a_1$ : $\gamma = 1$	76.97	74.45
-- case $a_2$ : $\gamma = 0$	79.27	76.03
(b) w/o discriminative learning		
-- case $b_1$ : removing	76.22	68.40
-- case $b_2$ : new class	78.34	73.11
(c) w/o iterative detection		
-- case $c_1$ : only once	77.52	70.31
-- case $c_2$ : no	76.17	63.50



# Experiments

- On ImageNet (200 classes):

Table 6. Accuracies (%) of different models on the 200-class ImageNet with 20% open-set noise. The best results are in **bold**.

Method	ResNet-50		Inception-v3	
	Top-1	Top-5	Top-1	Top-5
Cross-entropy	58.51	75.62	60.73	76.75
Backward	59.32	75.61	61.27	76.74
Forward	64.17	79.43	65.48	80.68
Bootstrapping	59.05	75.00	61.50	76.13
CNN-CRF	66.54	82.37	67.23	84.12
Ours	<b>70.29</b>	<b>86.04</b>	<b>71.43</b>	<b>87.87</b>



# Take Home Message

- **The open-set noisy label problem** – a more complex noisy label scenario that commonly occurs in real-world datasets
- **An iterative learning framework** to address the problem with three powerful modules: iterative noisy label detection, discriminative feature learning, and reweighting
- Modules are benefited from each other and jointly improved over iterations





***Thank you!***

