

Iterative Teaching by Label Synthesis

Weiyang Liu* Zhen Liu* Hanchen Wang*

Liam Paull Bernhard Schölkopf

Adrian Weller

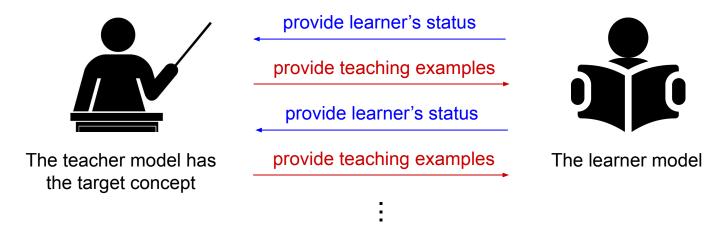






Iterative Machine Teaching (IMT)

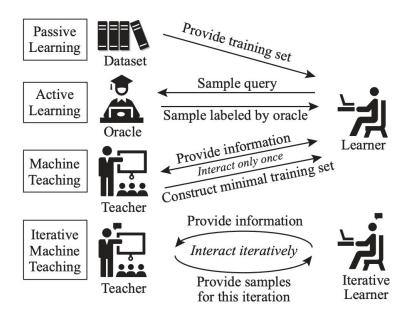
- How it works?
 - The learner is some machine learning model that aims to learn a set of target parameters.
 - The communication between the teacher and learner is contrained to be examples.



until the learner learns the target concept

Iterative Machine Teaching (IMT)

Comparison to other machine learning paradigms



The teacher and learner interact with each other iteratively!

Existing problems that motivate our method

- Classic IMT algorithms need to traverse the entire dataset to obtain the teaching examples for the learner.
 - Computationally expensive and not scalable to large datasets!
- Classic IMT algorithms typically restrict the teaching to example selection.
 - Low teaching capacity!
- Classic IMT algorithms solve a combinatorial problem by nature.
 - Nontrivial to learn a parameterized teaching policy!

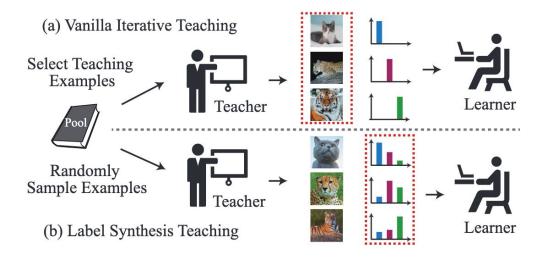
Existing problems that motivate our method

Classic IMT algorithms

- Need to traverse the entire dataset to obtain the teaching examples for the learner
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- Solve a combinatorial problem by nature
 - Nontrivial to learn a parameterized teaching policy!
- Typically restrict the form of teaching to example selection

Our Approach: Label Synthesis Teaching (LAST)

 We aim to avoid the traverse of the entire dataset by teaching the learner through label synthesis instead of example selection.



The red dottedframes indicate the teacher's efforts.

Why label synthesis?

- Effectively avoids traversing the dataset.
- Yields a computational cost that is independent of the dataset size.
- Provides a unified framework to think about label smoothing, knowledge distillation, etc.
- Has the same convergence speed-up guarantees as IMT.

Theorem 1 (Exponential teachability). Assume that the learner loss function ℓ_i has the property of interpolation, L_i -Lipschitz, and convexity. And f is order-1 μ strongly convex. Then LAST can achieve ET with $g(y) = c_1 \| \boldsymbol{w}^t - \boldsymbol{w}^* \|$, i.e., $\mathbb{E}\{\| \boldsymbol{w}^T - \boldsymbol{w}^* \|^2\} \leq (1 - c_1 \eta_t \bar{\mu} + c_1^2 \eta_t^2 L_{\max})^T \| \boldsymbol{w}^0 - \boldsymbol{w}^* \|^2$ where $L_{\max} = \max_i L_i$ and $\bar{\mu} = \sum_i \mu_i / n$. It implies that $(\log \frac{1}{c_2})^{-1} \log(\frac{1}{\epsilon})$ samples are needed to achieve $\mathbb{E}\{\| \boldsymbol{w}^T - \boldsymbol{w}^* \|^2\} \leq \epsilon$. $c_2 = 1 - c_1 \eta_t \bar{\mu} + c_1^2 \eta_t^2 L_{\max}$ and c_1 is adjusted such that $0 < c_1 \eta_t < \bar{\mu} / L_{\max}$.

Two LAST variants

LAST is solving the following optimizaiton in general (d is some discrepancy measure)

$$\min_{\{m{y}^1,\cdots,m{y}^T\}} d(m{w}^T,m{w}^*)$$
 learner's parameters after T steps target parameters

- Two ways of approximating the solution
 - One-step approximation with greedy LAST:

$$\min_{oldsymbol{y}^1} d(oldsymbol{w}^1, oldsymbol{w}^*)$$

Multi-step approximation with parameterized LAST:

$$\min_{\{\boldsymbol{y}^1,\cdots,\boldsymbol{y}^T\}} d(\boldsymbol{w}^T, \boldsymbol{w}^*) \longrightarrow \min_{\boldsymbol{\theta}} \left\| \boldsymbol{w}^T(\boldsymbol{\theta}) - \boldsymbol{w}^* \right\|_2^2$$

Greedy LAST

- Intuition: synthesize the label that leads to the maximum discrepancy reduction.
- Step 1: randomly select an example from the dataset.
- Step 2: generate the label of the selected example with

$$\min_{\boldsymbol{y}} \left\{ \left\| \boldsymbol{w}^t - \eta_t \frac{\partial \ell(\boldsymbol{x}, \boldsymbol{y} | \boldsymbol{w}^t)}{\partial \boldsymbol{w}^t} - \boldsymbol{w}^* \right\|_2^2 \right\}$$
 original gradients current learner's parameters target parameters

Step 3: update the learner with gradients using the synthesized label

$$oldsymbol{w}^t = oldsymbol{w}^{t-1} - \eta_t rac{\partial \ell(oldsymbol{x}^t, oldsymbol{y}^t | oldsymbol{w}^t)}{\partial oldsymbol{w}^t}$$

Parameterized LAST

- Intuition: use a parameterized teaching policy and learn it end-to-end by (1)
 unrolling multi-step gradient updates or (2) policy gradients.
- Nested Optimization: solve the following optimization by performing gradient descent on theta.

$$\min_{oldsymbol{ heta}} \left\| oldsymbol{w}^T(oldsymbol{ heta}) - oldsymbol{w}^*
ight\|_2^2$$

s.t. $\boldsymbol{w}^T(\boldsymbol{\theta}) = \arg\min_{\boldsymbol{w}} \mathbb{E}_{\{\boldsymbol{x}, \tilde{\boldsymbol{y}}\}} \big\{ \ell(\boldsymbol{x}, \pi_{\boldsymbol{\theta}}(\boldsymbol{x}, \tilde{\boldsymbol{y}}, \boldsymbol{w}^t, \boldsymbol{w}^*) | \boldsymbol{w}) \big\}$

Parameterized LAST

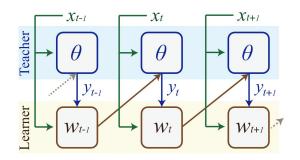
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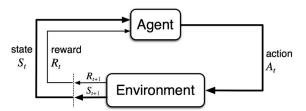
s.t. $m{w}^T(m{ heta}) = rg \min_{m{w}} \mathbb{E}_{\{m{x}, ilde{m{y}}\}} ig\{ \ell(m{x}, \pi_{m{ heta}}(m{x}, ilde{m{y}}, m{w}^t, m{w}^*) | m{w}) ig\}$

Ways to learn the parameterized LAST

 Unrolling the parameterized teaching policy into multi-step gradient updates.

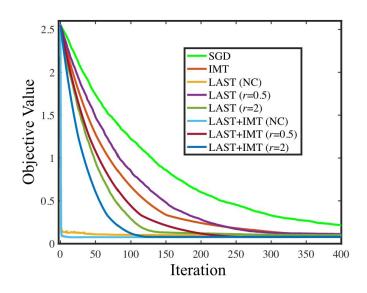


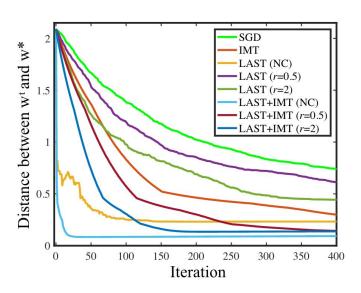
 Use the negative objective as the reward function and use policy gradients to update the teacher parameters.



Teaching least square regression learners

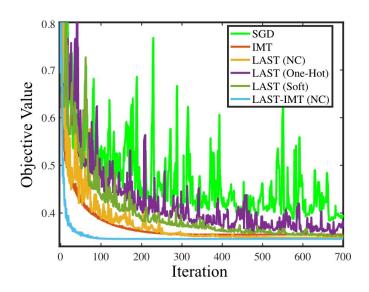
- SGD, IMT, Greedy LAST
- Greedy LAST + IMT: first use IMT to select examples and then use greedy LAST to synthesize labels.

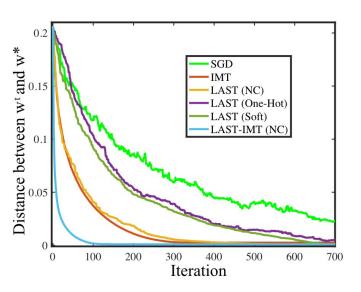




Teaching logistic regression learners

Greedy LAST

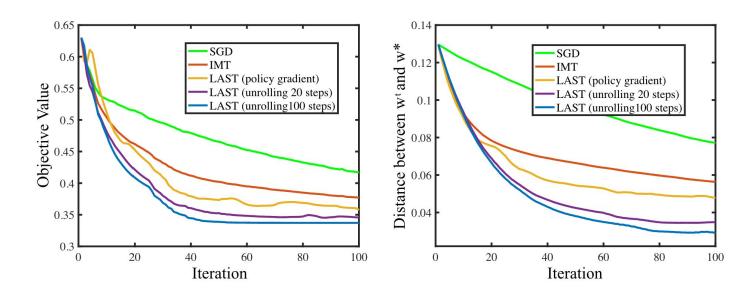




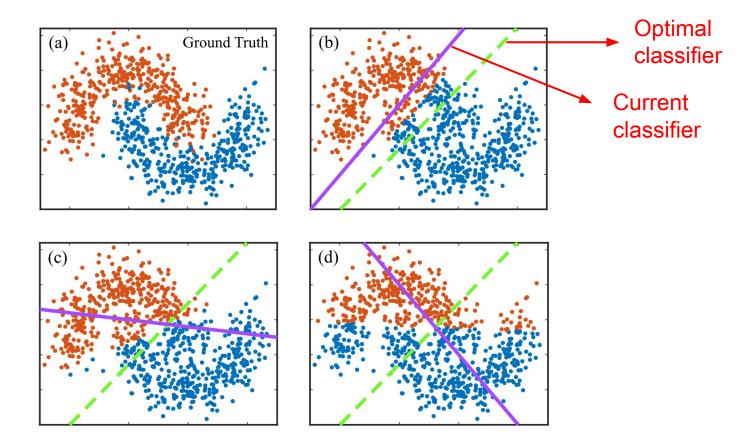
Teaching logistic regression learners

Parameterized LAST

Hyperparameters and settings are slightly different from the previous experiments.



How LAST changes the ground truth label



Summary

- We propose a novel iterative teaching paradigm by label synthesis.
- Advantages of LAST
 - Scalable: applicable to large datasets
 - Flexible: applicable in various settings and well connected to existing soft label methods
 - Easy to train: the parameterized LAST is end-to-end trainable
 - Theoretically guaranteed: yielding the same convergence speed-up as IMT
 - Empirically validated: achieving comparable or better empirical convergence as IMT